

# **DM556**

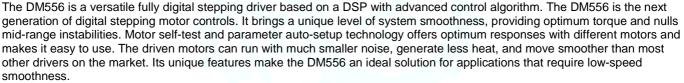
# Stepper Motor Driver



# Digital Driver Model DM556

Digital Technology, max. 50 VDC / 5.6 A

### **Product Description:**



Compared to the DM442, the DM556 provides a large voltage range and higher output current to able to drive a larger variety of stepper motors. Furthermore, the DSP of the DM556 is capable of driving the motors at higher speeds (above 3000 RPM) offering servo-like performance.

#### Features:

- Anti-Resonance, provides optimum torque and nulls mid-range instabilities
- Supply voltage up to +50 VDC (recommended not to exceed 45 V because of "back EMF")
- Output current programmable, from 0.5 A to 5.6 A
- Automatic idle-current reduction (in standstill mode) to reduce motor heating; function switchable (reduction rate can be software configured)
- Motor self-test and parameter auto-setup technology, offers optimum responses with different motors
- Pulse input frequency up to 200 kHz
- TTL compatible and optically isolated input
- Multi-Stepping allows a low resolution step input to produce a higher microstep output for smooth system performance
- Microstep resolutions programmable, from full-step to 102,400 steps/rev
- Suitable for 2-phase and 4-phase motors
- Support PUL/DIR and CW/CCW modes
- Over-voltage, over-current, phase-error protections

#### **Electrical Specifications:**

Parameters	Min	Тур.	Max	Unit
Output current	0.5	-	5.6 (4.0 RMS)	Α
Supply voltage	+20		+50	VDC
Logic signal current	7	10	16	mA
Puls input frequency	0	-	200	kHz
Insulation resistance	500			ΜΩ

#### **Further Specifications:**

Parameters	Min	Тур.	Max
Microsteps / 1,8 °	Full-step		102.400
Pulse / Direction (PUL / DIR)		X	
Double pulse (CW / CCW)		X	
NEMA sizes	17		34
Motor type Mecheltron	42BYGH-XXX		86BYGH-XXX

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Technische Änderungen vorbehalten



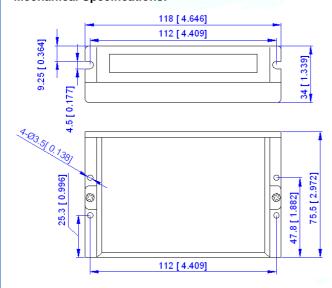
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### **Mechanical Specifications:**



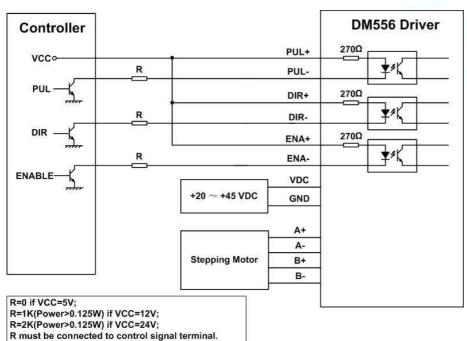
Unit: mm [inch]

## **Applications:**

Suitable for a wide range of stepper motors of NEMA sizes 17, 23 und 34 (42 x 42 mm to 86 x 86 mm). It can be used in various kinds of machines, such as X-Y tables, engraving machines, labeling machines, laser cutters, pick-place devices, and so on. Particularly well suited for applications where low noise levels, less heat development, high speed and high precision are desired.

### **Typical Connection Schematic:**

A typical system consists of stepper motor, stepper motor driver, power supply and controller. The following image shows a typical connection schematic:



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